

## An experimental investigation of sensor fault assessment for piezoelectric interface-based structural health monitoring

Nghiên cứu thực nghiệm về chẩn đoán lỗi cảm biến cho việc giám sát sức khỏe kết cấu bằng kỹ thuật giao diện áp điện

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### Abstract

The operational functionality of the sensors is critically important to a structural health monitoring (SHM) system. Sensor defects will result in considerable changes in measured signals, leading to an inaccurate estimation of a structure's health status. This study presents an experimental investigation on sensor fault diagnosis for piezoelectric interface-based SHM. Firstly, an impedance monitoring method via the smart piezoelectric interface is introduced. Secondly, experiments are conducted on a steel bolted connection to investigate the effect of sensor defects on impedance responses. Finally, an impedance feature is extracted and used to diagnose and differentiate the sensor defects from the structural damages. The results show that the sensor faults will cause significant changes in the measured impedance signals; the presence of sensor defects can be effectively distinguished from the existence of structural damages by using the extracted impedance feature.

**Keywords:** Sensor fault, electromechanical, piezoelectric interface, PZT, impedance response, structural health monitoring.

### Tóm tắt

Sự hoạt động ổn định của các cảm biến là rất quan trọng đối với hệ thống theo dõi sức khỏe công trình. Các lỗi cảm biến sẽ gây ra những thay đổi đáng kể trong những tín hiệu đo được, dẫn đến những chẩn đoán sai lệch về tình trạng sức khỏe của công trình. Bài báo này trình bày một nghiên cứu thực nghiệm về chẩn đoán lỗi cảm biến cho việc theo dõi sức khỏe kết cấu bằng kỹ thuật giao diện áp điện. Đầu tiên, phương pháp giám sát trở kháng bằng kỹ thuật giao diện áp điện thông minh được giới thiệu. Tiếp theo, các ảnh hưởng của lỗi cảm biến đối với trở kháng của kết cấu được nghiên cứu thông qua các thí nghiệm đo trở kháng, được tiến hành trên một mối nối bu-lông bằng thép. Cuối cùng, đặc trưng trở kháng được trích lọc và sử dụng để chẩn đoán các lỗi cảm biến và phân biệt chúng với các hư hỏng của công

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trình. Kết quả thí nghiệm cho thấy các lỗi cảm biến có thể gây ra những thay đổi đáng kể đến tín hiệu trở kháng và các lỗi cảm biến này có thể được phân biệt một cách hiệu quả với những hư hỏng công trình bằng cách sử dụng đặc trưng trở kháng.

*Từ khóa:* Lỗi cảm biến; điện-ơ; giao diện áp điện; cảm biến áp điện; ứng xử trở kháng; theo dõi sức khỏe công trình.

## 1. Introduction

The electromechanical (EM) impedance method has been extensively investigated for structural integrity assessment of the critical connections in civil structures [1-6]. The method relies on acquiring high-frequency impedance responses from the host structure, that are sensitive to minor structural damages. Traditionally, a piezoelectric sensor (i.e., PZT) is directly-bonded to the host structure's surface to perform a required impedance measurement. However, the direct attachment of the PZT often leads to weak EM impedance responses and cause difficulties in predetermining effective frequency bands for damage detection tasks [7]. To overcome these issues, the piezoelectric interface technique (i.e., the PZT interface) has been developed as an alternative attachment method for the PZT sensor [5, 8, 9]. The PZT is indirectly attached to the host structure via a substrate structure called 'interface'. The structural and geometrical properties of the PZT interface are adjusted to create strong resonances in the desired effective frequency range. The piezoelectric interface technique can be easily integrated with a wireless impedance sensing system to perform autonomous and real-time structural health monitoring (SHM) [10-12].

However, there still exist challenges which limit *in-situ* applications of the piezoelectric interface technique. To ensure the success of a damage identification process, it is critical to confirm the operational condition of the piezoelectric sensor. Sensor defects would result in observable changes in the measured EM impedance responses, which would be inaccurately interpreted as the existence of

structural damages. Many research efforts have been made to detect sensor faults in SHM systems [13-16]. While most of them have focused on the vibration method, only a few studies have evaluated the operational condition of piezoelectric sensors for the impedance method. Giurgiutiu *et al.* [17] studied the influence of the bonding layer on the EM impedance and proposed a sensor debonding identification method by tracking the appearance of the PZT's resonance. Park *et al.* [18] developed a sensor diagnostic strategy tailored to the impedance method by tracking the changes in the gradients of imaginary admittance (i.e., an inverse of impedance). Ai *et al.* [19] extracted the features of the real admittance responses and used them to diagnose and differentiate the sensor faults from the structural damage. Despite those research attempts, the diagnosis of sensor defects has not been reported for the piezoelectric interface-based impedance monitoring so far.

This study has been motivated to experimentally investigate the effect of sensor faults on impedance-based SHM using the piezoelectric-based smart interface. The study aims to provide an experimental foundation for impedance monitoring practices using the smart piezoelectric interface with the existence of sensor faults. At first, the impedance monitoring technique via the piezoelectric-based smart interface is outlined. Next, experiments are conducted on a steel bolted connection to investigate the effects of structural damage and sensor defects on electromechanical (EM) impedance responses. Lastly, an impedance feature is extracted from the measured EM impedance to diagnose and differentiate the sensor defects from the structural damage.

## 2. Piezoelectric interface-based health monitoring technique

The piezoelectric interface technique was proposed to monitor the health condition of a structure with predetermined sensitive frequency bands [8]. In the technique, the PZT is indirectly attached to the host structure via a substrate called ‘interface’ (i.e., the PZT interface). Figure 1 shows the interaction between the PZT interface (represented by  $k_i, c_i, m_i$ ) and a host structure (represented by  $k_s, c_s, m_s$ ). The interface is designed with two outside sections (i.e., the bonded sections) for the attachment and a middle free section (i.e., the flexible section) to provide free vibrations for the PZT sensor (see Fig. 1). The structural and geometrical properties of the PZT interface can be adjusted to predetermine sensitive frequency bands for impedance measurement. The prototype design of the PZT interface can be found in an existing publication [20].

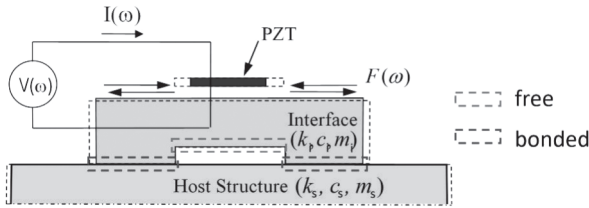


Fig. 1. PZT interface-host structure interaction under the voltage excitation

To acquire the impedance responses, a harmonic voltage  $V(\omega)$  is applied to the PZT sensor and the output electric current  $I(\omega)$  is then measured by an impedance analyzer. The EM impedance of the whole system,  $Z(\omega)$ , is a combined function of the structural mechanical (SM) impedance of the piezoelectric patch,  $Z_a(\omega)$ , and that of the coupled interface-host structure  $\bar{Z}(\omega)$ , as described below:

$$Z(\omega) = \frac{V}{I} = \left\{ i\omega \frac{w_a l_a}{t_a} \left[ \hat{\epsilon}_{33}^T - \frac{1}{Z_a(\omega)/\bar{Z}(\omega) + 1} d_{31}^2 \hat{Y}_{11}^E \right] \right\}^{-1} \quad (1)$$

where  $\hat{Y}_{xx}^E = (1 + i\eta)Y_{xx}^E$  is the complex Young’s modulus of the PZT patch at a zero electric field;  $\hat{\epsilon}_{xx}^T = (1 - i\delta)\epsilon_{xx}^T$  is the complex dielectric constant at zero stress;  $d_{3x}$  is the piezoelectric coupling constant in the x-direction at zero stress; and  $w_a, l_a,$  and  $t_a$  are the width, length, and thickness of the PZT patch, respectively. The parameters  $\eta$  and  $\delta$  are structural damping loss factor and dielectric loss factor of piezoelectric material, respectively. The SM impedance of the coupled interface-host structure system  $\bar{Z}(\omega)$  can be computed from the following equation [21]:

$$\bar{Z}(\omega) = \frac{(-\omega^2 m_i + i\omega c_i + k_i)(-\omega^2 m_s + i\omega(c_i + c_s) + (k_i + k_s)) - (i\omega c_i + k_i)^2}{i\omega(-\omega^2 m_s + i\omega(c_i + c_s) + (k_i + k_s))} \quad (2)$$

Equation (2) shows that the SM impedance of the coupled interface-host structure system is characterized by the masses, damping, and stiffness of both the interface ( $k_i, c_i, m_i$ ) and the host structure ( $k_s, c_s, m_s$ ). Thus, the change in these parameters caused by structural damages can be represented by the change in the EM impedance obtained from the PZT sensor. By quantifying the variations of EM impedance signals, the structural damage occurred in the host structure can be detected.

To successfully implement a damage detection job, it is important to confirm the operation of the PZT sensor. In a realistic situation, the sensor and its bonding layer can be degraded under the effects of overloading conditions, material deteriorations, and environmental changes. The sensor breakage/quality degradation will cause changes in piezoelectric properties. Also, the bonding layer’s defects will affect the force transmission from the PZT to the interface structure. As a result, observable changes in the measured EM impedance could be inaccurately interpreted as the occurrence of structural damages.

### 3. Experimental sensor defect diagnosis for piezoelectric interface

#### 3.1. PZT interface-based health monitoring of steel bolted connection

A bolted connection of a steel beam (H–200×180×8×10 mm) was selected to perform impedance monitoring via the piezoelectric interface technique. The connection was fastened by 8 bolts ( $\phi 20$  mm) at the top and the bottom flanges, respectively (see Fig. 2a). All bolts were fastened by the torque level of 160 Nm (i.e., a healthy state). To acquire the EM impedance from the joint, a PZT interface was fabricated and mounted to the surface of the splice plate (see Fig. 2b). The material of the interface structure is aluminium. The flexible section of the interface has the width of 33 mm, the length of 30 mm, and the thickness of 4 mm; and the two bonded sections have a width of 33 mm, a length of 30 mm, and a thickness of 5 mm. The PZT sensor (PZT-5A) has the width of 25 mm, the height of 25 mm, and the thickness of 0.51 mm. The sensor was bonded to the interface via a bonding layer (instant adhesive Loctite 401). For impedance

measurements, the HIOKI 3532 analyzer was used to generate the harmonic excitation of 1 V and to measure the EM impedance responses (see Fig. 2c).

As described in Table 1, three testing scenarios were carried out for the experimental investigation, including the sensor debonding, the sensor breakage, and the structural damage tests. The sensor debonding test was performed by reducing the bonding area of the adhesive layer. Four debonding cases of the sensor were investigated, including no debonding (i.e., an intact state), 39.2% debonding, 66.4% debonding, and 84% debonding cases. The sensor breakage test was simulated by reducing the size of the PZT. Four breakage cases of the PZT were studied, including no breakage (i.e., an intact state), 36% breakage, 64% breakage, and 84% breakage cases. The structural damage test was conducted by reducing the torque of Bolt 2 (see Fig. 2a) from 160 Nm to 110 Nm, 60 Nm, and 0 Nm. During the experimental tests, the room temperature was controlled at 21°C to avoid any effect of temperature changes on the measurements.

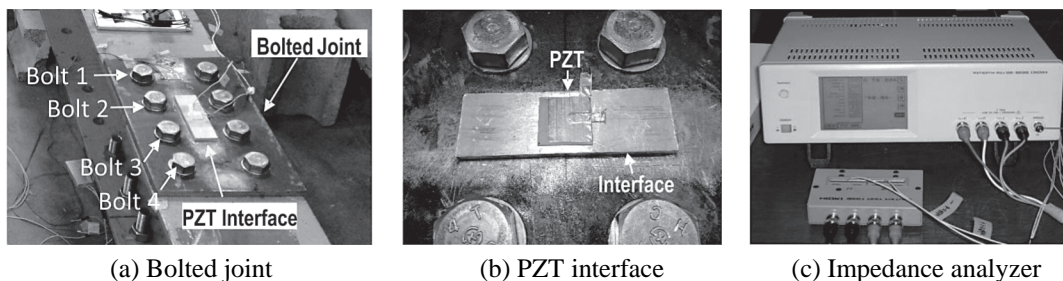


Fig 2. Experimental setup for the lab-scaled steel beam

Table 1. Descriptions of test scenarios

| Test Scenarios    | Description   |
|-------------------|---|
| Sensor Debonding  | PZT's bonding area was reduced by 0%, 39.2%, 66.4%, and 84%       |
| Sensor Breakage   | PZT's area was reduced by 0%, 36%, 64%, and 84%                   |
| Structural Damage | Bolt 2' torque was reduced from 160 Nm to 110 Nm, 60 Nm, and 0 Nm |

#### 3.2. Effect of sensor defects on impedance responses

The real impedance signatures in 10-50 kHz measured under the sensor debonding cases are shown in Fig. 3a. The signatures show two clear resonant peaks under the intact state of the PZT (i.e., a perfect bonding condition). When the debonding level of the PZT was increased up to 84%, the magnitude of the resonant impedance peaks was reduced, as zoomed in

Fig. 3a. It is known that the imaginary part of impedance contains much information about the sensor's health status. Hence, the effect of the sensor debonding on the imaginary admittance (i.e., an inverse of impedance) was examined in Fig. 3b. It is observed that the sensor debonding caused upward shifts in the slope of the imaginary admittance.

Figure 4a shows the real impedance signatures in 10-50 kHz for different levels of the sensor breakage. Obviously, the sensor breakage caused upward shifts in the real impedance signatures, as zoomed in Fig.4a. The shifting effect was found to be more considerable for lower frequencies. The imaginary admittance signatures in 10-50 kHz

were also examined for the different breakage levels of the PZT, as shown in Fig. 4b. It is obvious that the sensor breakage caused downward shifts in the slope of the imaginary admittance, as zoomed in Fig. 4b.

For the structural damage cases, the real impedance signatures in 10-50 kHz were shown in Fig. 5a. The reduction in bolt torque caused leftward shifts in the real impedance at the resonances. The torque reduction also significantly modified the imaginary admittance signatures at the resonances, as observed in Fig. 5b. Interestingly, the structural damage did not cause any shifts in the slope of the imaginary admittance.

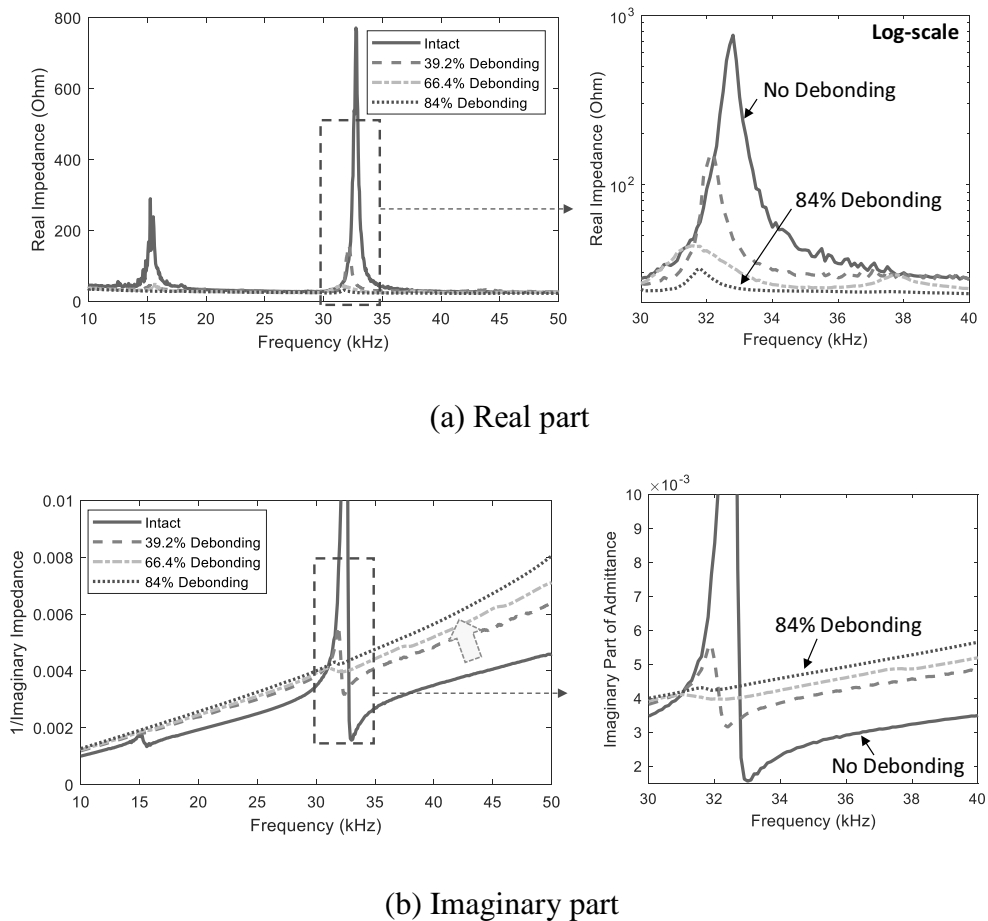
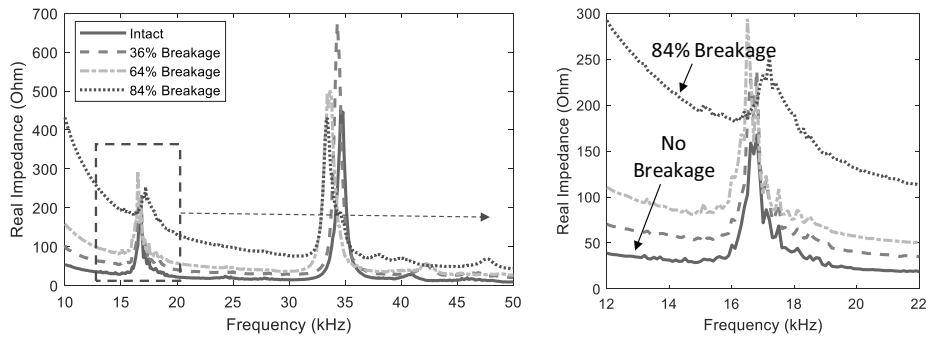
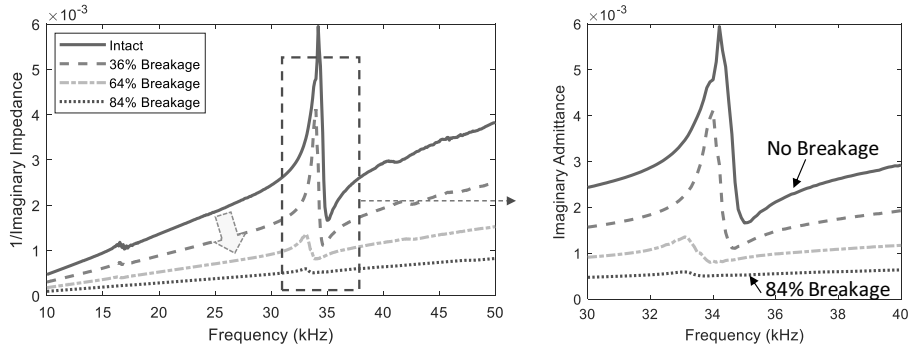


Fig 3. Measured impedance signatures under the sensor debonding cases

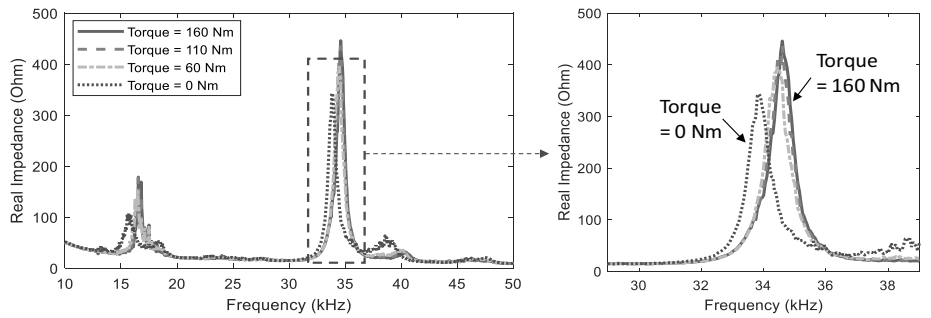


(a) Real part

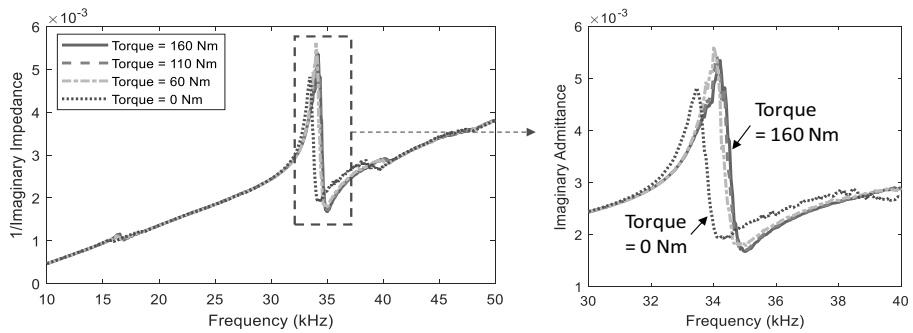


(b) Imaginary part

Fig 4. Measured impedance signatures under the sensor breakage cases



(a) Real part



(b) Imaginary part

Fig 5. Measured impedance signatures under the structural damage cases (Bolt 2 loosened)

### 3.3. Sensor fault diagnosis using an impedance feature

To diagnose and differentiate the sensor defects from the structural damage for the bolted joint, the slope of the imaginary admittance was extracted. For that, the slope of the imaginary admittance signatures was estimated by using the linear approximation method. The computed slopes were then plotted according to the severities of the structural damage (i.e., torque-loss), the sensor debonding, and the sensor breakage, as depicted in Fig. 6. The results showed that the slope of the imaginary impedance remained generally stable about  $8 \times 10^{-5}$  for the structural damage cases (i.e., no sensor defects). When the sensor was debonded, the slope of the imaginary admittance was rapidly increased. Particularly, the slope was changed from  $8 \times 10^{-5}$  to  $16 \times 10^{-5}$  as the debonding severity rose from 0% to 84%. For the sensor breakage cases, the slope was decreased from  $8 \times 10^{-5}$  to  $1.8 \times 10^{-5}$  as the breakage level was changed from 0% to 84%.

It is experimentally confirmed that the slope of the imaginary admittance can be used to diagnose the sensor defects for the impedance monitoring via the piezoelectric interface. Particularly, an increased value of the slope of the imaginary admittance is an indication for the sensor debonding while a decreased value of the slope is responsible for the sensor breakage, and stable values of the slope can be interpreted as no sensor defects.

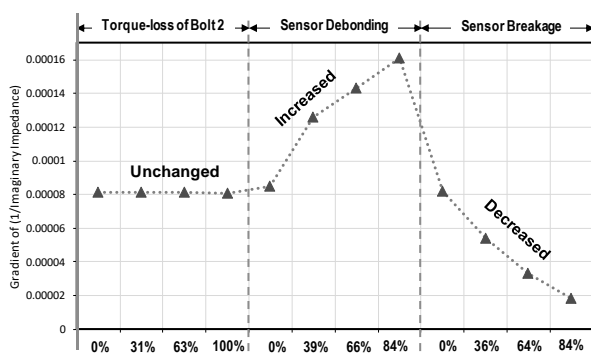


Fig 6. Sensor fault diagnosis using the slope of imaginary admittance

## 4. Conclusion

This study presented an experimental investigation on the effects of sensor faults on impedance-based SHM using the piezoelectric-based smart interface. The experimental investigation showed that the sensor faults caused significant changes in measured EM impedance responses. Specifically, the sensor debonding caused a decrease in the magnitude of resonances and an increase in the slope of the imaginary admittance. The sensor breakage caused upward shifts in the patterns of the real EM impedance and a decrease in the slope of the imaginary admittance. By contrast, the structural damage did not cause any variations in the slope of the imaginary admittance. The slope of the imaginary admittance was then extracted to assess the sensor defects for the PZT interface. The obtained results showed that the presence of the sensor defects can be effectively distinguished from the existence of the structural damages by using the extracted impedance feature. This study provides an experimental background for impedance-based SHM practices, via the piezoelectric interface technique, with the presence of sensor defects.

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